

# Towards systematic error estimates in asymptotically safe gravity-matter systems

HEP Seminar, National Centre for Nuclear Research  
December 16, 2025

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**Marc Schiffer**, Radboud University Nijmegen

Based on

M. Riabokon, MS, F. Wagner: **Phys.Rev.D 112 (2025) 10, 106003**

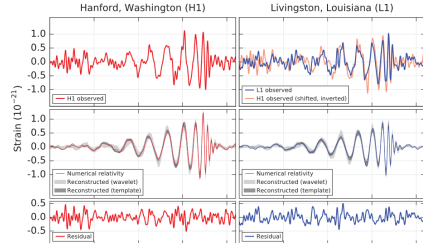
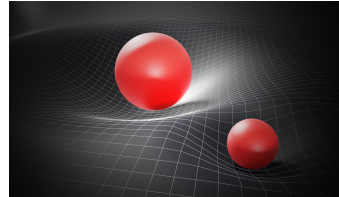
G. de Brito, M. Reichert, MS: **arXiv: 2510.09572**

Radboud Universiteit



# Why Quantum Gravity with matter?

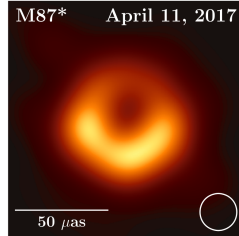
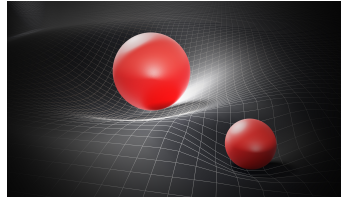
## General Relativity



LIGO, 2016

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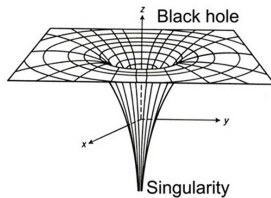
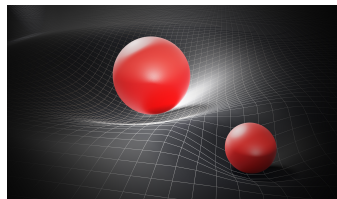
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EHT, 2019

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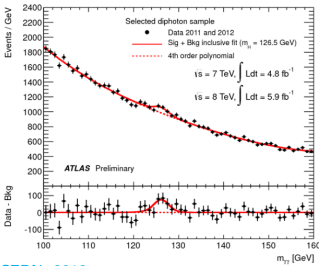


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$$\text{Scale of QG: } M_{\text{Pl}} = \sqrt{\frac{\hbar c}{g}}$$

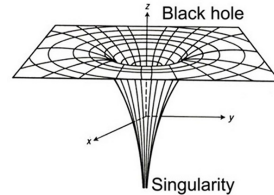
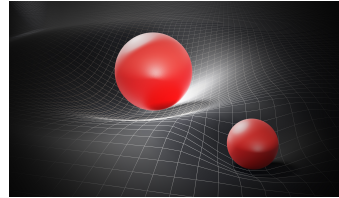
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					GAUGE BOSONS



CERN, 2012

## General Relativity



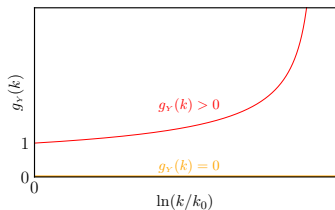
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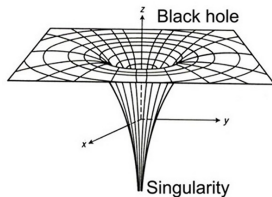
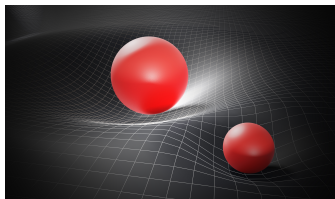
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Scale of divergence:  $E_{LP} \gg M_{Pl}$

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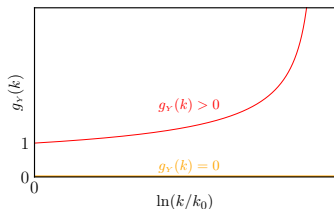
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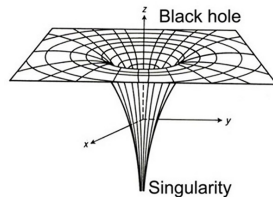
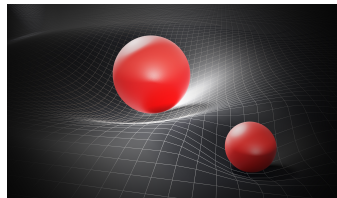
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Quantum nature of spacetime: might provide UV-completion for GR and SM!

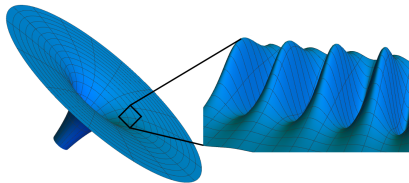
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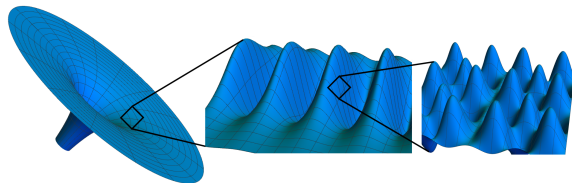
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# Asymptotically Safe Quantum Gravity

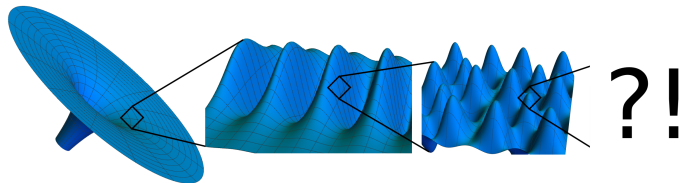


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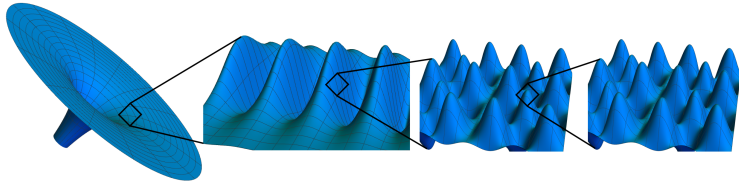
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# Asymptotically Safe Quantum Gravity



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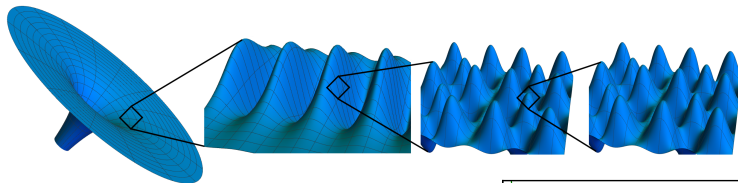
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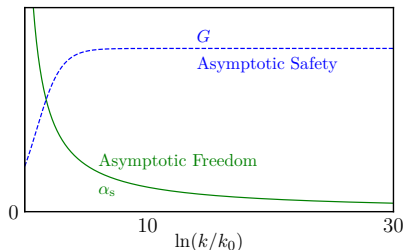
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- Key idea of asymptotic safety:  
**Quantum** realization of  
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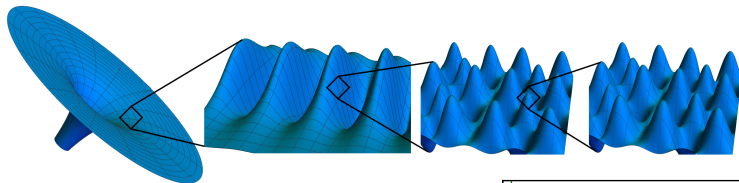
Asymptotic freedom:

free fixed point,  $\alpha_{s,*} = 0$

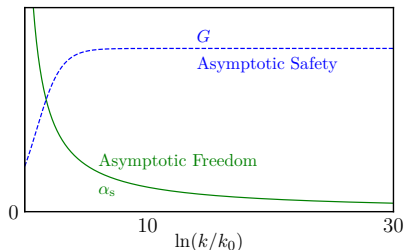
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# Asymptotically Safe Quantum Gravity



- Perturbative quantum gravity:  
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- Key idea of asymptotic safety:  
**Quantum** realization of  
**scale symmetry**
  - ▶ imposes infinitely many conditions on theory
  - ▶ Examples for AS:  
gauge-Yukawa systems (perturbative)  
[\[Litim, Sannino; 2014\]](#)  
Gross-Neveu, etc.  
[\[Braun, Gies, Scherer; 2010\]](#), see also review [\[Eichhorn, 2019\]](#)



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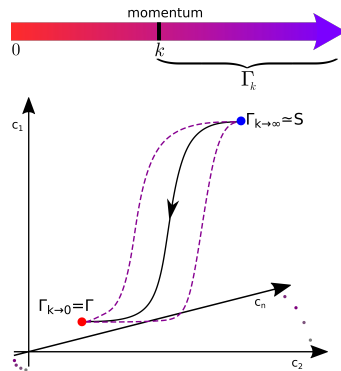
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Use different methods in concerted sfashion to extract evidence for and physical features of asymptotically safe quantum gravity.

see also [Ambjorn, Gizbert-Studnicki, Goerlich, Nemeth; 2024]

# Tool: Functional Renormalization Group

Main idea:  
include quantum fluctuations step by step

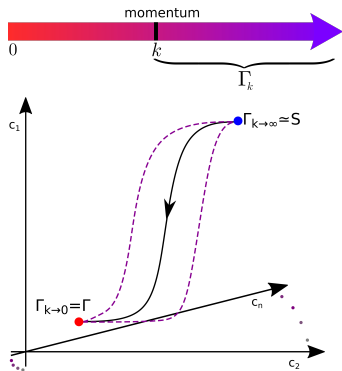


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$$e^{-\Gamma_k[\phi]} \sim \int \mathcal{D}\varphi e^{-S[\varphi] - \frac{1}{2} \int_p \varphi(-p) R_k(p^2) \varphi(p)}, \quad R_k(p^2) \begin{cases} > 0 \text{ if } p^2 < k^2 \text{ (supression)} \\ = 0 \text{ if } p^2 > k^2 \text{ (no supression)} \end{cases}$$



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## Flow Equation

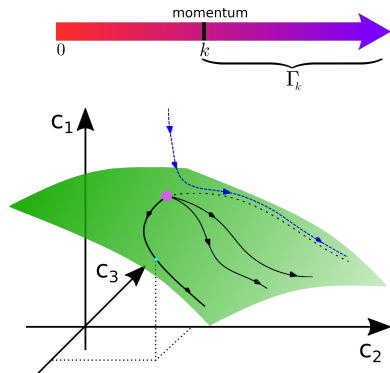
[Wetterich, 1993], [Ellwanger, 1993], [Morris, 1994], [Reuter, 1996]

$$k \partial_k \Gamma_k = \frac{1}{2} \text{STr} \left( \left( \Gamma_k^{(2)} + R_k \right)^{-1} k \partial_k R_k \right)$$
$$= \frac{1}{2} \text{ (Feynman diagram: a circle with a cross on top) }$$

→ search for fixed points  $k \partial_k g_i = 0$

→ describe RG-flow in theory-space

$\Gamma_k$  : requires truncation  $\Rightarrow$  not exact



# Predictivity in asymptotic safety

scale invariance



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our universe at low energies



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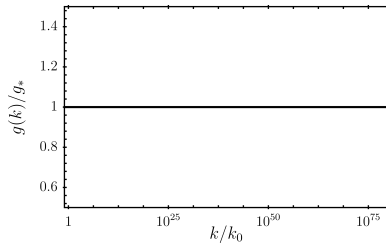
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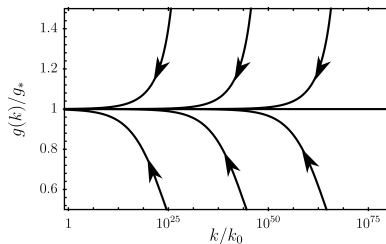
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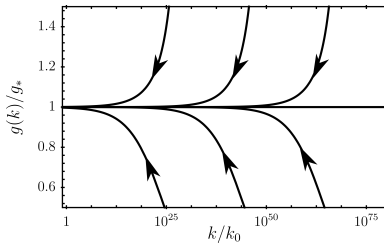
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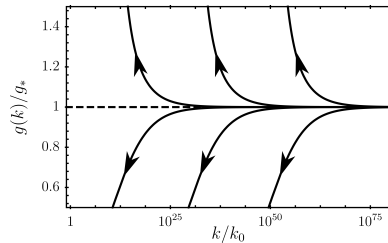
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Relevant direction:  
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- More technically: predictivity encoded in critical exponents  $\Theta_I$ :

$$g_j(k) = g_j^* + \sum_I c_I V_j^I \left( \frac{k}{k_0} \right)^{-\Theta_I} \quad \text{with} \quad \Theta_I = -\text{eig} \left( \left( \frac{\partial \beta_{g_j}}{\partial g_i} \right) \Big|_{\mathbf{g}=\mathbf{g}^*} \right)$$

Irrelevant direction:  
prediction in IR

$$\Theta_I < 0$$

Relevant direction:  
free parameter

$$\Theta_I > 0$$


# AS in gravity-matter systems

**matter**  
tells spacetime how to curve

$$G_{\mu\nu} = 8\pi G_N T_{\mu\nu}$$

**spacetime**  
tells matter how to move

- Key questions for gravity-matter systems:



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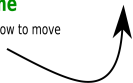
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- Key questions for gravity-matter systems:
  - ▶ Does the gravity fixed-point allow for the inclusion of SM-matter?  
[\[Doná, Eichhorn, Percacci; 2013\]](#), [\[Meibohm, Pawłowski, Reichert; 2016\]](#), [\[Biemanns, Platania, Saueressig; 2017\]](#)  
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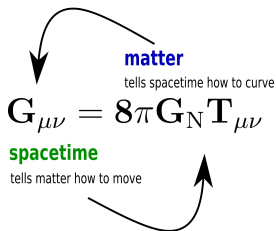
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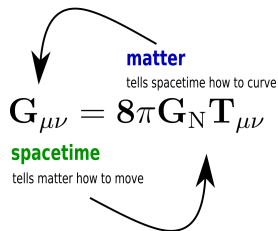
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[Shaposhnikov, Wetterich; 2009], [Harst, Reuter; 2011], [Eichhorn, Held; 2017, 2018], [Eichhorn, Versteegen; 2017], . . .  
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- ▶ Robustness of phenomenological implications?

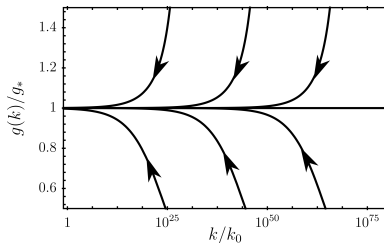
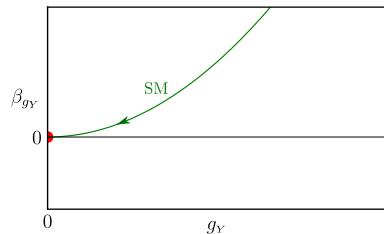
[Kotłarski, Kowalska, Rizzo, Sessolo; 2023], [Riabokon, MS, Wagner; 2025], [de Brito, Reichert, MS; 2025]

# The $U(1)$ sector of the Standard Model

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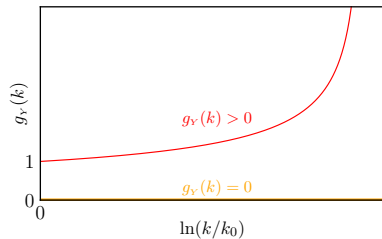
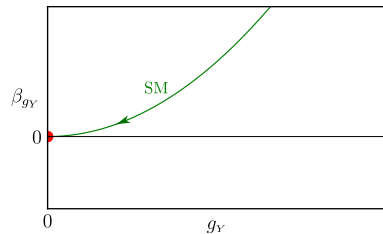
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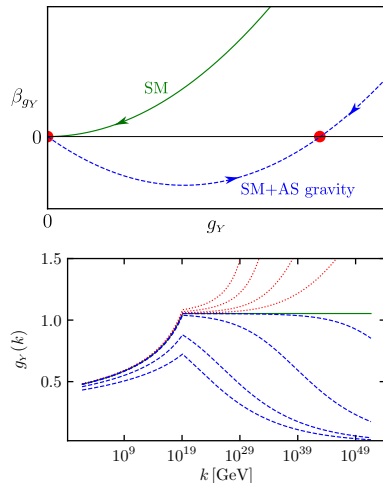


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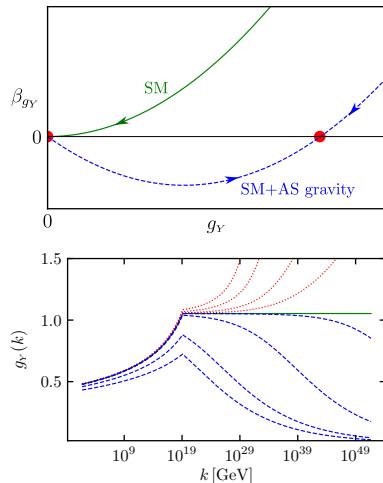


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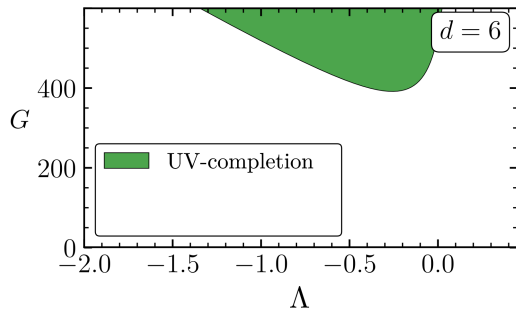
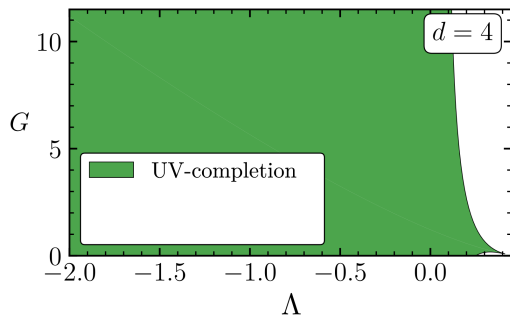
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Metric fluctuations might induce a UV completion of the  $U(1)$ -sector.  
 $\Rightarrow$  Upper bound on  $g_Y(k)$  (i.e., constraints on gravity) [Eichhorn, Versteegen; 2017]

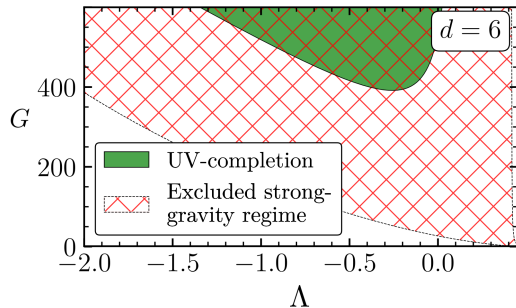
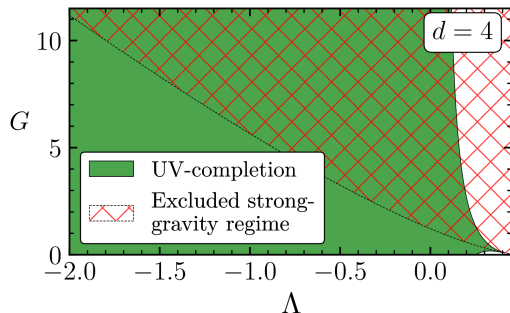
## Example: The $U(1)$ sector in $d > 4$

- $\beta_{g_Y} = g_Y \left( \frac{d-4}{2} - f_g(d) \right) + \mathcal{O}(g_Y^3)$   
⇒ UV-completion shifts into more strongly coupled regime



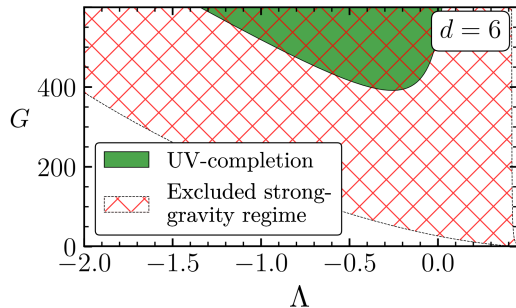
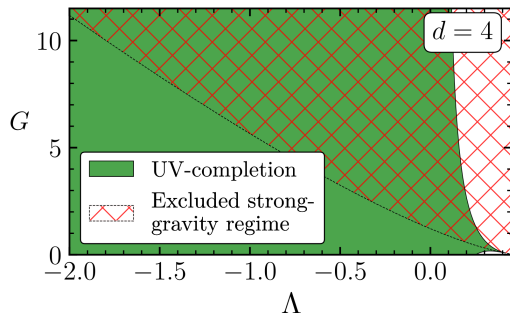
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$U(1)$  gauge sector might remain UV-incomplete in  $d \geq 6$ , even in the presence of gravity.

[Eichhorn, MS; 2019]

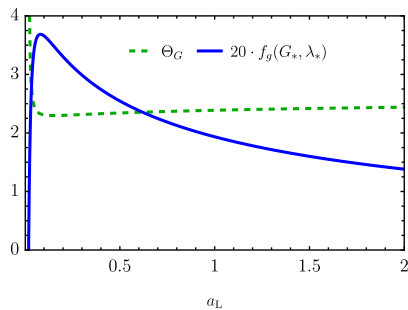
## Robustness of $f_g$ : Litim-type shapefunction

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- Litim-type shapefunction:  $r_k(z) = a_L(1 - z)\Theta(1 - z)$

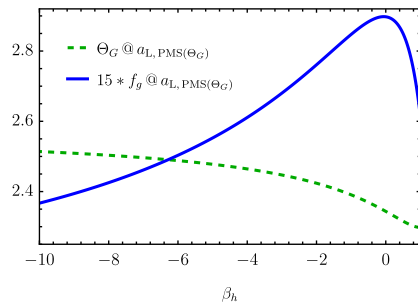
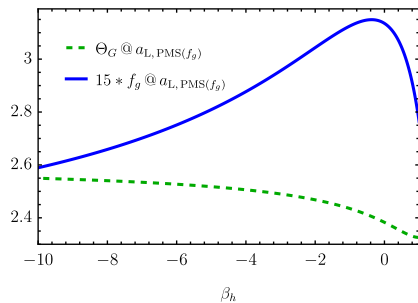
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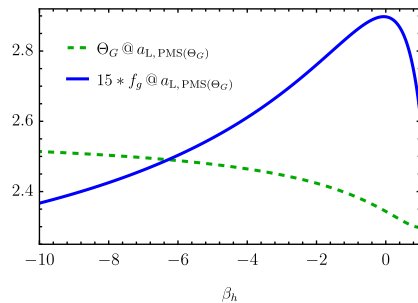
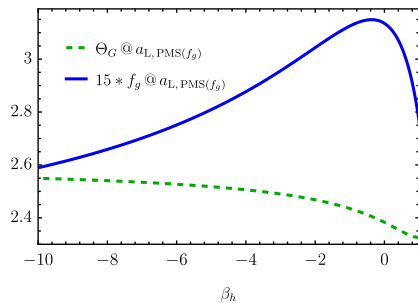
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- Track each as function of  $\beta_h$
- Can additionally minimize  $\beta_h$ -dependence.



## Robustness of $f_g$ : Adding matter

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- Start from previous picture, and add scalars, fermions gauge fields
- In short: scalars and gauge fields move curves to the right, fermions to the left.
- SM matter content: fermions dominate, hence no PMS point
- Caveat: background approximation likely to break down for SM matter content

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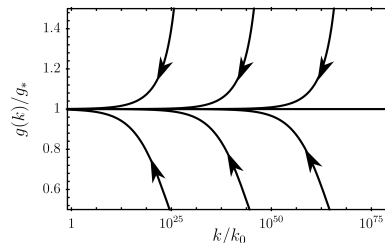
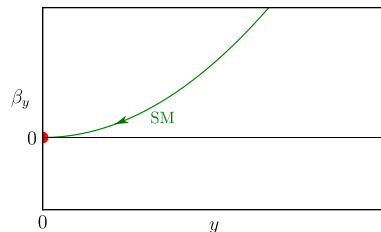
## Summary

- For minimal matter content: PMS point of  $f_g$  in  $a_i$  and  $\beta_h$
- This point is global maximum of  $f_g$ ; similarities between shape-functions

# Towards the Yukawa sector of the Standard Model

Single Yukawa coupling  $y$ :

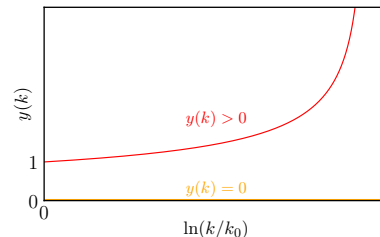
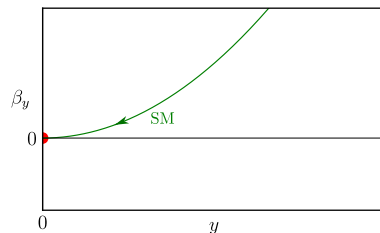
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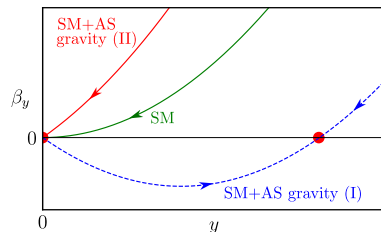
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$$f_y \begin{cases} = \text{const.} > 0, & \text{for } k > M_{\text{Pl}} \wedge \Lambda < \Lambda_{\text{crit}} \\ = \text{const.} < 0, & \text{for } k > M_{\text{Pl}} \wedge \text{for } \Lambda > \Lambda_{\text{crit}} \\ \approx 0, & \text{for } k < M_{\text{Pl}} \end{cases}$$

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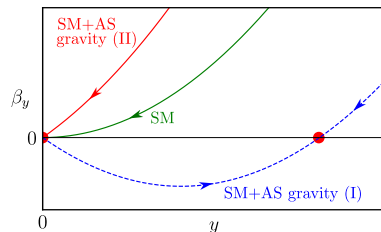


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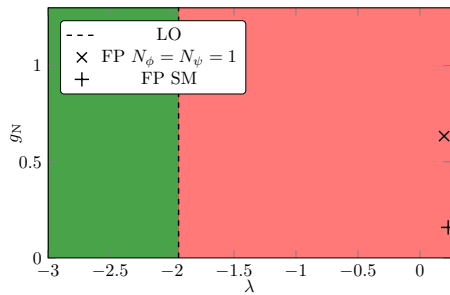


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UV completion of the simple Yukawa system: constraints on gravitational dynamics

Additionally: top mass might be retro-dicted [Eichhorn, Held, 2017]

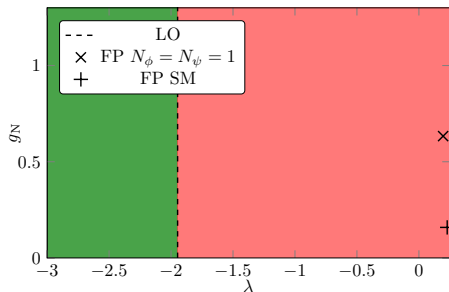
# Simple Yukawa system: state of the art (LO)



- Simplest approximation:

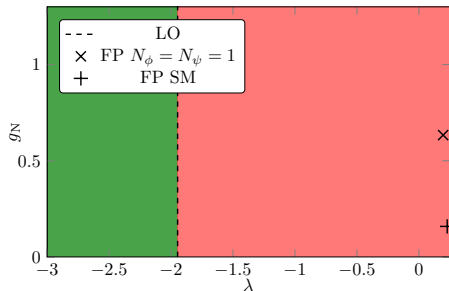
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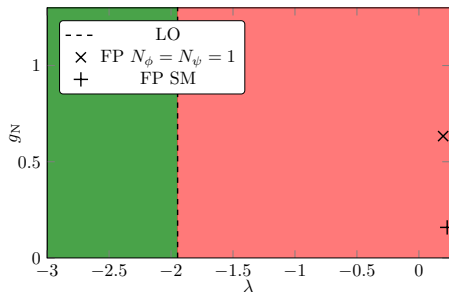
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finite Yukawa coupling  
+ retrodiction [Eichhorn, Held; 2017]  
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 $f_{y,*} < 0$  see, e.g., [Christiansen et al.; 2019]

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Leading order:  $\Theta_{y,\text{MM}} = -0.58$  and  $\Theta_{y,\text{SM}} = -0.22$

This would result in vanishing Yukawa couplings in IR

$\Rightarrow$  no-go theorem for fundamental Yukawa interactions in ASQG!?

$$\theta_I = -\text{eig}(M_{ij}) , \quad \text{with} \quad M_{ij} = \left( \frac{\partial \beta_{g_j}}{\partial g_i} \right) \Big|_{\mathbf{g}=\mathbf{g}^*}$$

- At LO:  $\theta_y = f_y g$ ;
- NLO:  $g^2$  contributions to  $\Theta_y$ ;

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- At LO:  $\theta_y = f_y g$ ;
- NLO:  $g^2$  contributions to  $\Theta_y$ ;
- Possible sources:
  - ▶ direct contributions to  $M_{11}$ 
    - contribution  $\sim y g_{\text{ind}}$  to  $\beta_y$  with  $g_{\text{ind},*} \neq 0$
  - ▶ off-diagonal contributions in  $M_{ij}$  - contribution to  $\beta_y$  can be independent of  $y$  itself

# Direct contributions: induced operators

- Operators share symmetries of kinetic terms
- Feature Gaussian fixed point for  $g = 0$  and *shifted* Gaussian fixed point for  $g \neq 0$
- Existence of fixed point for induced operators at  $g_*$ : non-trivial test for ASQG (stability of truncations)

[Eichhorn, Gies; 2011], [Eichhorn; 2021], [Christiansen, Eichhorn; 2017], [Eichhorn, Held; 2017], [Eichhorn, MS; 2019], . . .

- Assume induced coupling  $b$

$$\beta_b = d_{\mathcal{O}} b + c_1 b + \mathcal{O}(g^2), \quad \Rightarrow \quad b_* = -g_* \frac{c_1}{d_{\mathcal{O}}} + \mathcal{O}(g^2).$$

- Contribution to  $\theta_y$ :

$$\theta_y|_{\text{ind}} = -c_2 g_* b_* = -g_*^2 \frac{c_1 c_2}{d_{\mathcal{O}}} + \mathcal{O}(g^3)$$

# Off-diagonal contributions

- Break symmetries of kinetic terms
- Always feature Gaussian fixed point; interacting fixed point possible, but not needed!
- Consider coupling  $\kappa$ : contributes linearly to  $\beta_y$ , and  $y$  contributes linearly to  $\beta_\kappa$

$$M = \begin{bmatrix} a_{11} g & a_{12} g \\ a_{21} g & d_{\mathcal{O}} + a_{22} g \end{bmatrix} .$$

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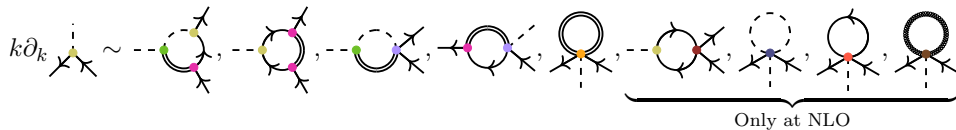
$$M = \begin{bmatrix} a_{11} g & a_{12} g \\ a_{21} g & d_{\mathcal{O}} + a_{22} g \end{bmatrix}.$$

- This yields

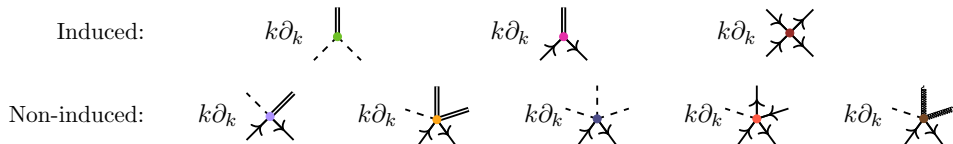
$$\theta_y|_{\text{non-induced}} = -g_*^2 \frac{a_{12} a_{21}}{d_{\mathcal{O}}} + \mathcal{O}(g^3)$$

# Truncation via vertex-resummation

## Yukawa flow equation



## Resummed vertices



# Simple Yukawa system: Summary of NLO Operators

- **Induced**
- contributions to  $\beta_y$  with  $g_* \neq 0$

Vertex	Operator	Coupl.
$h_{\mu\nu}\bar{\psi}\psi$	$R^{\mu\nu}\psi\gamma_\mu D_\nu\psi$	$\sigma_{\text{Ric}}$
	$R\psi\cancel{D}\psi$	$\sigma_{\text{R}}$
$h_{\mu\nu}\phi^2$	$R^{\mu\nu}\partial_\mu\phi\partial_\nu\phi$	$\rho_{\text{Ric}}$
	$R\partial_\mu\phi\partial^\mu\phi$	$\rho_{\text{R}}$
$(\psi\psi)^2$	$(\psi\gamma_\mu\psi)^2 + (i\psi\gamma_\mu\gamma_5\psi)^2$	$\lambda_+$
$\phi^2\bar{\psi}\psi$	$\partial_\mu\phi\partial^\mu\phi\bar{\psi}\cancel{D}\psi$	$\chi_{1/2}$
$\phi^4$	$(\partial_\mu\phi\partial^\mu\phi)^2$	$\text{K}_2$
$h_{\mu\nu}^2\bar{\psi}\psi$	$R^2\bar{\psi}\cancel{D}\psi$	$\sigma_{R^2,i}$
$h_{\mu\nu}^2\phi^2$	$R^2\partial_\mu\phi\partial^\mu\phi$	$\rho_{R^2,i}$

see [Eichhorn, MS; 2022] for references

contribute via  $\eta_i$  only  $\Rightarrow$  neglect

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- **Non induced**

- contributions to  $\beta_y$  with  $\hat{g}_{i,*} = 0$

Vertex	Operator	Coupl.
$\phi\bar{\psi}\psi$	$\square\phi\psi\psi$	$y_{\square,1}$
	$\phi\psi\square\psi$	$y_{\square,2}$
$h_{\mu\nu}\phi\psi\psi$	$R\phi\psi\psi$	$y_{\text{R}}$
$h_{\mu\nu}^2\phi\bar{\psi}\psi$	$R^2\phi\psi\psi$	$y_{\text{R}^2}$
	$C_{\mu\nu\rho\sigma}^2\phi\psi\psi$	$y_{\text{C}^2}$
$\phi^3\bar{\psi}\psi$	$(\partial_\mu\phi)^2\phi\psi\psi$	$y_{\phi^2}$
$\phi(\psi\psi)^2$	$(\psi\cancel{D}\psi)\phi\psi\psi$	$y_{\bar{\psi}\psi}$
$A^2\phi\psi\psi$	$(F_{\mu\nu}F^{\mu\nu})\phi\psi\psi$	$y_{A^2}$

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$h_{\mu\nu}^2\phi\bar{\psi}\psi$	$R^2\phi\psi\psi$	$y_{\text{R}^2}$
	$C_{\mu\nu\rho\sigma}^2\phi\psi\psi$	$y_{\text{C}^2}$
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$\phi(\psi\psi)^2$	$(\psi\cancel{D}\psi)\phi\psi\psi$	$y_{\bar{\psi}\psi}$
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contribute via  $\eta_i$  only  $\Rightarrow$  neglect

Induced operators shift FP, but admit lower-triangular stability sub-matrix

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$h_{\mu\nu}\bar{\psi}\psi$	$R^{\mu\nu}\psi\gamma_\mu D_\nu\psi$	$\sigma_{\text{Ric}}$
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$h_{\mu\nu}\phi^2$	$R^{\mu\nu}\partial_\mu\phi\partial_\nu\phi$	$\rho_{\text{Ric}}$
	$R\partial_\mu\phi\partial^\mu\phi$	$\rho_{\text{R}}$
$(\psi\psi)^2$	$(\psi\gamma_\mu\psi)^2 + (i\psi\gamma_\mu\gamma_5\psi)^2$	$\lambda_+$
$\phi^2\bar{\psi}\psi$	$\partial_\mu\phi\partial^\mu\phi\bar{\psi}\cancel{D}\psi$	$\chi_{1/2}$
$\phi^4$	$(\partial_\mu\phi\partial^\mu\phi)^2$	$K_2$
$h_{\mu\nu}^2\bar{\psi}\psi$	$R^2\bar{\psi}\cancel{D}\psi$	$\sigma_{R^2,i}$
$h_{\mu\nu}^2\phi^2$	$R^2\partial_\mu\phi\partial^\mu\phi$	$\rho_{R^2,i}$

- **Non induced**

- contributions to  $\beta_y$  with  $\hat{g}_{i,*} = 0$

Vertex	Operator	Coupl.
$\phi\bar{\psi}\psi$	$\square\phi\psi\psi$	$y_{\square,1}$
	$\phi\psi\square\psi$	$y_{\square,2}$
$h_{\mu\nu}\phi\psi\psi$	$R\phi\psi\psi$	$y_{\text{R}}$
$h_{\mu\nu}^2\phi\bar{\psi}\psi$	$R^2\phi\psi\psi$	$y_{\text{R}^2}$
	$C_{\mu\nu\rho\sigma}^2\phi\psi\psi$	$y_{\text{C}^2}$
$\phi^3\bar{\psi}\psi$	$(\partial_\mu\phi)^2\phi\psi\psi$	$y_{\phi^2}$
$\phi(\psi\psi)^2$	$(\psi\cancel{D}\psi)\phi\psi\psi$	$y_{\bar{\psi}\psi}$
$A^2\phi\psi\psi$	$(F_{\mu\nu}F^{\mu\nu})\phi\psi\psi$	$y_{A^2}$

see [Eichhorn, MS; 2022] for references

contribute via  $\eta_i$  only  $\Rightarrow$  neglect

Induced operators shift FP, but admit lower-triangular stability sub-matrix

Modulo momentum-dependences: No further  $q^2$  contribution to  $\theta_u$

# Yukawa system: Main results

- Fixed point exists for minimal matter and SM matter
- Critical exponents of higher-order operators: close to canonical mass dimension
- Yukawa couplings are relevant at asymptotically safe fixed point!

$$\theta_{y,\text{MM}} = 3.1_{-1.1}^{+1.8}, \quad \theta_{y,\text{SM}} = 2.2_{-1.0}^{+1.3}$$

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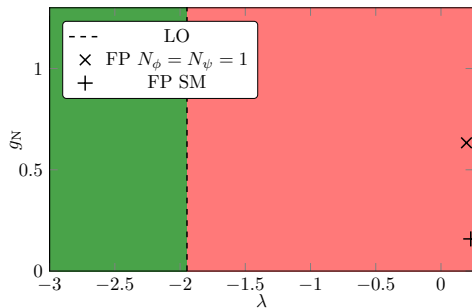
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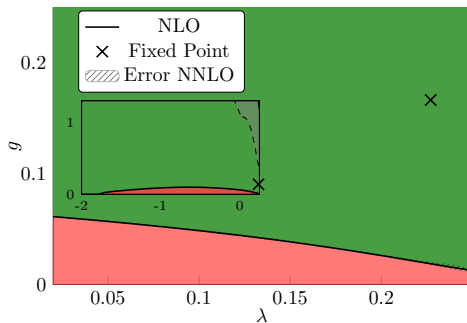
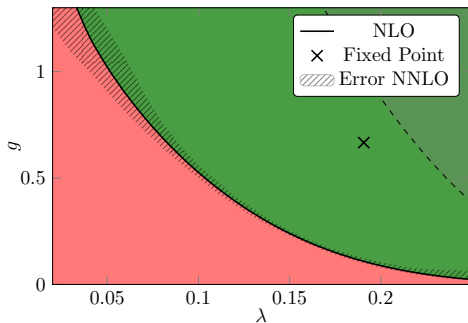
- Contributions from various couplings:

$$\begin{aligned} \theta_{y,SM} &= -1.3g + g^2 \left( \underbrace{-13}_{y_R} + \underbrace{0.81}_{y_{\square}} + \underbrace{32}_{y_{R^2}} \underbrace{-17}_{y_{C^2}} + \underbrace{40}_{y_{\bar{\psi}\psi}} + \underbrace{1.8}_{y_{A^2}} \right. \\ &\quad \left. \underbrace{-1.6}_{\rho_{Ric}} + \underbrace{1.0}_{\rho_R} \underbrace{-0.40}_{\sigma_{Ric}} + \underbrace{0.53}_{\sigma_R} + \underbrace{0.13}_{\lambda_+} \right) \\ &= -1.3g + 44g^2. \end{aligned}$$

# Yukawa coupling at NLO

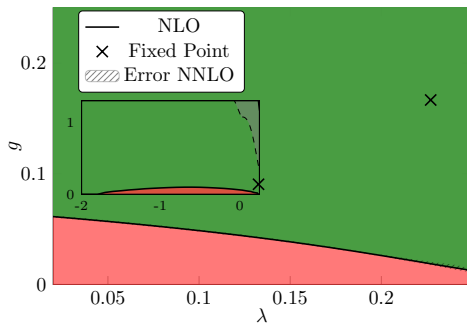
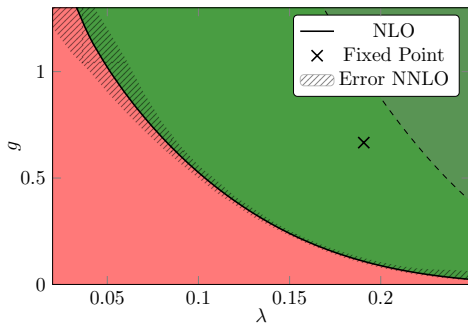


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- NLO contributions to stability matrix: generate new regime where  $\theta_y > 0$
- Fixed point lies inside that new regime!
- LO:  $\theta_y < 0$ , NLO:  $\theta_y > 0$ ; What about NNLO (i.e.,  $g^3$ -contributions)?

# Estimating NNLO effects ('error bars')

- previously observed:  $R \phi \bar{\psi} \psi$ ,  $R^2 \phi \bar{\psi} \psi$  and  $C^2 \phi \bar{\psi} \psi$  dominate
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$$M_{\text{NLO}} = \begin{pmatrix} 1.3 g & 1.1 g & 0.54 g & 1.3 g & -2.2 g & -0.14 g & -0.048 g \\ -23 g & 2 - 0.73 g & -5.5 g & 0.46 g & 8.5 g & -0.014 g & -0.0093 g \\ 3.0 g & 1.6 g & 2 + 1.8 g & 0 & 0 & 0 & 0 \\ 95 g & 36 g & 25 g & 4 + 2.4 g & -43 g & 0 & 0 \\ 31 g & 13 g & 5.7 g & 34 g & 4 - 5.9 g & 0 & 0 \\ -1100 g & -680 g & -370 g & 630 g & 410 g & 4 - 0.39 g & 0 \\ -150 g & -46 g & -23 g & 5.5 g & 18 g & 0 & 4 - 1.4 g \end{pmatrix}$$

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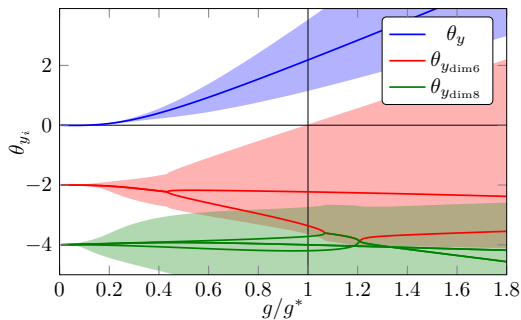
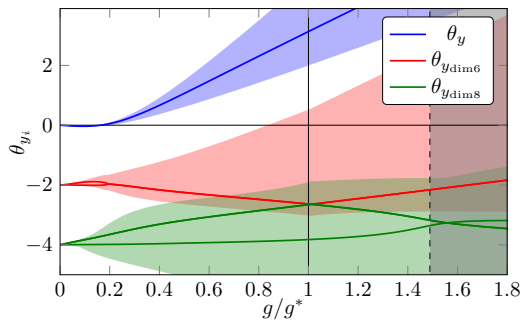
$$\tilde{M}_{\text{NLO}} = \begin{pmatrix} 1.3 g & 2.3 g & -1.5 g & -4.0 g & -8.7 g & -21 g & -0.62 g \\ -11 g & 2 - 0.75 g & 6.9 g & -14 g & 5.6 g & -1.0 g & -0.056 g \\ -1.1 g & -1.3 g & 2 + 1.8 g & 0 & 0 & 0 & 0 \\ -16 g & -13 g & 10 g & 4 + 3.0 g & 39 g & 0 & 0 \\ -14 g & -11 g & -11 g & -37 g & 4 - 6.4 g & 0 & 0 \\ -7.4 g & -9.5 g & -6.5 g & -20 g & -12 g & 4 - 0.38 g & 0 \\ -12 g & -7.5 g & 4.8 g & -5.9 g & 0.62 g & 0 & 4 - 1.4 g \end{pmatrix}$$

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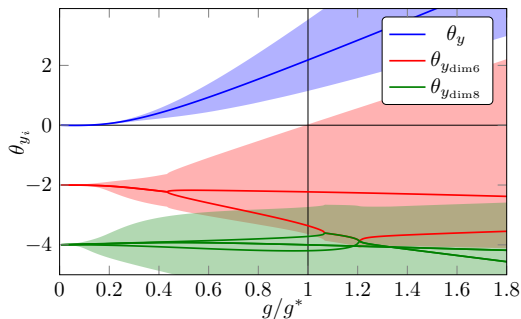
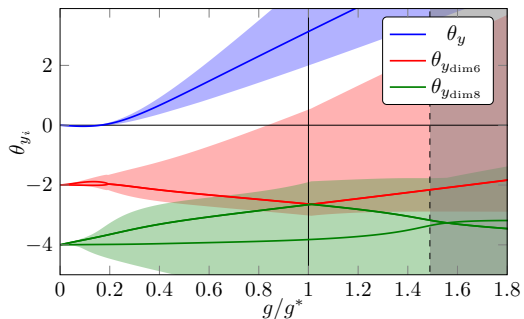
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- Simulate effect of NNLO operator on  $\theta_y$  (pick appropriate range for  $\#_r$ )

$$M = \begin{pmatrix} & & & & & & & 0 \\ & & & & & & & \#g \\ & & & & & & & 0 \\ & & & \tilde{M}_{\text{NLO}} & & & & \#g \\ & & & & & & & \#g \\ & & & & & & & \#g \\ & & & & & & & \#g \\ & & & & & & & \#g \\ \#g & \#g & \#g & \#g & \#g & \#g & \#g & 6 + \#g \end{pmatrix}$$

# Results of (N)NLO simulations

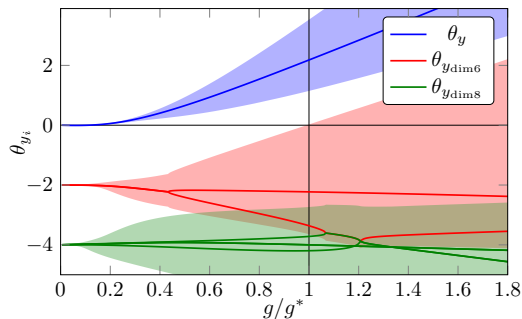
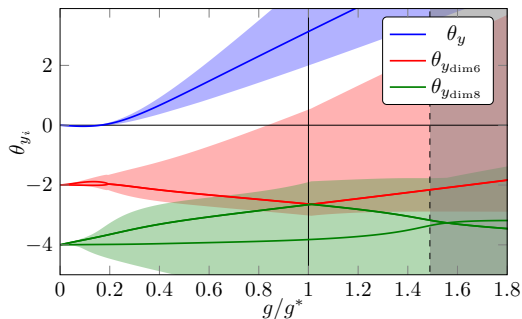


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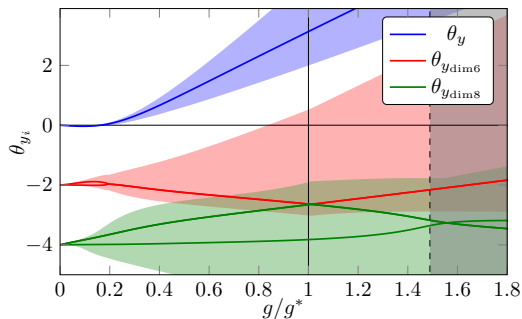
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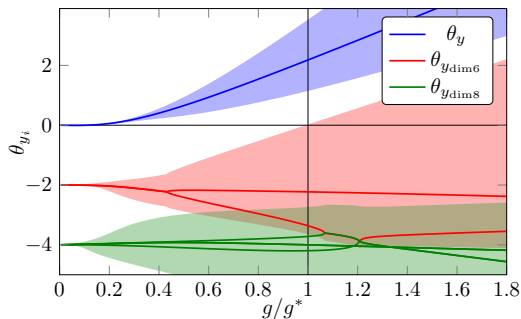


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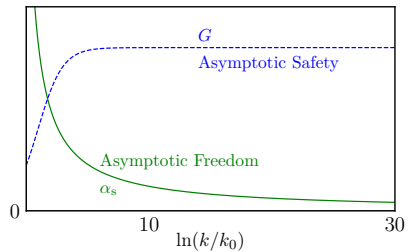
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- (N)NLO simulations: insights into robustness
- large(ish) error-bars on  $\theta_y$
- small error-bars on region where  $\theta_y \approx 0$

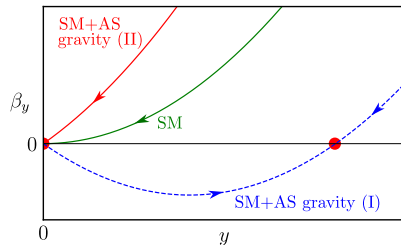
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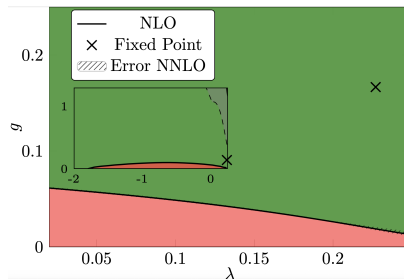
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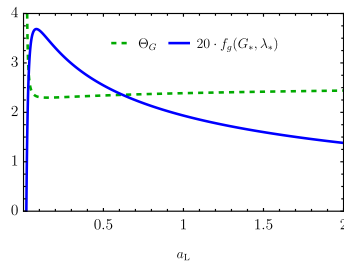
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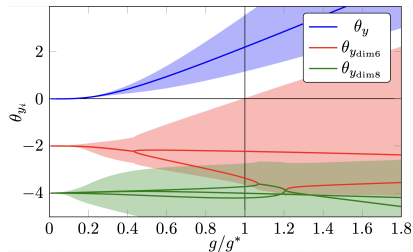
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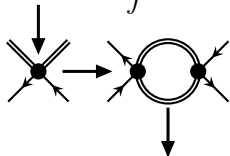
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**Stay tuned!**  
**Thank you for your attention!**

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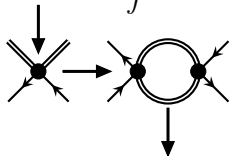


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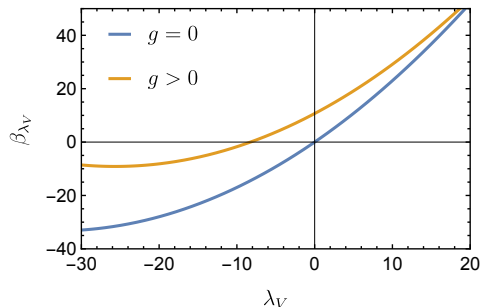
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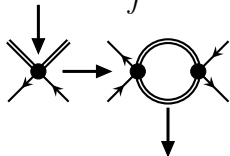


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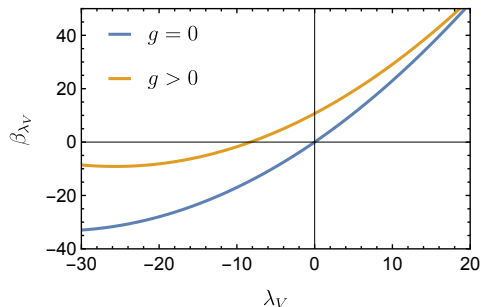
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- For  $g > 0$ :  $\lambda_{V,*} \neq 0$

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- both cases: well-behaved extensions of the Reuter FP!

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- Plug FP-values into non-induced operators, and compute critical exponents at

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- **SM matter**

$$\theta_{y_i} = (2.2, -2.2, -3.4, -3.7, -4.0 \pm 6.4 i, -4.2).$$

$$\begin{aligned} \theta_y &= -1.3g + g^2 \left( \underbrace{-13}_{y_R} + \underbrace{0.81}_{y_{\square}} + \underbrace{32}_{y_{R^2}} \underbrace{-17}_{y_{C^2}} + \underbrace{40}_{y_{\bar{\psi}\psi}} + \underbrace{1.8}_{y_{A^2}} \right. \\ &\quad \left. \underbrace{-1.6}_{\rho_{\text{Ric}}} + \underbrace{1.0}_{\rho_R} \underbrace{-0.40}_{\sigma_{\text{Ric}}} + \underbrace{0.53}_{\sigma_R} + \underbrace{0.13}_{\lambda_+} \right) \\ &= -1.3g + 44g^2. \end{aligned}$$

- both cases:  $\Theta_1 > 0$  is aligned mostly with  $y$